Yokohama Publishers

# A SHRINKING PROJECTION ALGORITHM FOR VARIATIONAL INEQUALITIES AND FIXED POINT PROBLEMS 

YONGHONG YAO


#### Abstract

A shrinking projection algorithm is presented for solving the variational inequality and fixed point problem of the pseudocontractive operator. Strong convergence analysis of the suggested algorithm is given.


## 1. Introduction

Let $H$ be a real Hilbert space with inner product $\langle\cdot, \cdot\rangle$ and induced norm $\|\cdot\|$. Let $C$ be a nonempty closed convex subset of $H$. Let $A: C \rightarrow H$ be a nonlinear operator. By definition, the variational inequality problem is to find $u \in C$ such that

$$
\begin{equation*}
\langle A u, v-u\rangle \geq 0, \forall v \in C \tag{1.1}
\end{equation*}
$$

The set of solutions of the variational inequality (1.1) is denoted by $V I(A, C)$.
Variational inequality theory has emerged as an important tool in studying a wide class of obstacle, unilateral and equilibrium problems, which arise in several branches of pure and applied sciences in a unified and general framework. Several numerical methods have been developed for solving variational inequalities and related optimization problems, see $[1,4-8,10,11,14-16,19,21]$ and the references therein.

Recall that a mapping $T: C \rightarrow C$ is said to be pseudocontractive if

$$
\begin{equation*}
\left\langle T u-T u^{\dagger}, u-u^{\dagger}\right\rangle \leq\left\|u-u^{\dagger}\right\|^{2} \tag{1.2}
\end{equation*}
$$

for all $u, u^{\dagger} \in C$.
The interest of pseudocontractions lies in their connection with monotone operators; namely, $T$ is a pseudocontraction if and only if the complement $I-T$ is a monotone operator. There are a large number references associated with algorithmic approaches to the fixed points of pseudocontractive operators, see, e.g., $[2,3,17,18,22]$.

The main purpose of this paper is to study the variational inequality problem (1.1) and the fixed point problem of the pseudocontractive operator. We suggest an iterative algorithm by using the shrinking projection method in Hilbert spaces. We demonstrate the strong convergence of the presented the shrinking projection

[^0]algorithm for finding the common element of the variational inequality problem (1.1) and the fixed point problem of the pseudocontractive operator.

## 2. Preliminaries

Let $C$ be a nonempty closed convex subset of a real Hilbert space $H$. Let $T$ : $C \rightarrow C$ be a nonlinear mapping. Denote the set of fixed points of $T$ by $\operatorname{Fix}(T)$, that is, $\operatorname{Fix}(T):=\{x \in C \mid x=T x\}$.

A mapping $T: C \rightarrow C$ is said to be $L$-Lipschitzian if

$$
\left\|T u-T u^{\dagger}\right\| \leq L\left\|u-u^{\dagger}\right\|
$$

for all $u, u^{\dagger} \in C$, where $L>0$ is a constant. If $L=1, T$ is said to be nonexpansive.
A mapping $A: C \rightarrow H$ is said to be inverse strongly monotone if there exists $\zeta>0$ such that

$$
\langle u-v, A u-A v\rangle \geq \zeta\|A u-A v\|^{2}
$$

for all $u, v \in C$.
Note that (1.2) is equivalent to the following:

$$
\begin{equation*}
\left\|T u-T u^{\dagger}\right\|^{2} \leq\left\|u-u^{\dagger}\right\|^{2}+\left\|(I-T) u-(I-T) u^{\dagger}\right\|^{2} \tag{2.1}
\end{equation*}
$$

for all $u, u^{\dagger} \in C$.
The metric (or nearest point) projection from $H$ onto $C$ is the mapping $\operatorname{proj}_{C}$ : $H \rightarrow C$ which assigns to each point $x \in C$ the unique point $\operatorname{proj}_{C} x \in C$ satisfying the property

$$
\left\|x-\operatorname{proj}_{C} x\right\|=\inf _{y \in C}\|x-y\| .
$$

It is clear that the metric projection proj is a typical firmly nonexpansive mapping. The characteristic inequality of the projection is

$$
\left\langle u-\operatorname{proj}_{C} u, u^{\dagger}-\operatorname{proj}_{C} u\right\rangle \leq 0
$$

for all $u \in H$ and $u^{\dagger} \in C$.
A mapping $T$ is said to be demiclosed if, for any sequence $\left\{x_{n}\right\}$ which weakly converges to $\tilde{x}$, if the sequence $\left\{T\left(x_{n}\right)\right\}$ strongly converges to $x^{\dagger}$, then $T(\tilde{x})=x^{\dagger}$.

It is well-known that in a real Hilbert space $H$, the following equality holds:

$$
\begin{equation*}
\left\|\xi u+(1-\xi) u^{\dagger}\right\|^{2}=\xi\|u\|^{2}+(1-\xi)\left\|u^{\dagger}\right\|^{2}-\xi(1-\xi)\left\|u-u^{\dagger}\right\|^{2} \tag{2.2}
\end{equation*}
$$

for all $u, u^{\dagger} \in H$ and $\xi \in[0,1]$.
We need the following lemmas for our main results:
Lemma 2.1 ([22]). Let $C$ be a nonempty closed convex subset of a real Hilbert space H. Let $T: C \rightarrow C$ be a continuous pseudocontractive mapping. Then
(i) $\operatorname{Fix}(T)$ is a closed convex subset of $C$.
(ii) $(I-T)$ is demiclosed at zero.

Lemma 2.2 ([18]). Let $C$ be a nonempty closed convex subset of a real Hilbert space H. Let $T: C \rightarrow C$ be an L-Lipschitz pseudocontractive operator. Then, the operator $(1-\xi) I+\xi T((1-\eta) I+\eta T)$ is quasi-nonexpansive when $0<\xi<\eta<\frac{1}{\sqrt{1+L^{2}}+1}$. That is,

$$
\left\|(1-\xi) x+\xi T((1-\eta) x+\eta T x)-u^{\dagger}\right\| \leq\left\|x-u^{\dagger}\right\|
$$

for all $x \in C$ and $u^{\dagger} \in \operatorname{Fix}(T)$.
For the convenience, in the sequel we use the following expressions:

- $x_{n} \rightharpoonup x^{\dagger}$ denotes the weak convergence of $x_{n}$ to $x^{\dagger}$;
- $x_{n} \rightarrow x^{\dagger}$ denotes the strong convergence of $x_{n}$ to $x^{\dagger}$.

Let $\left\{C_{n}\right\}$ be a sequence of nonempty closed convex subsets of a Hilbert space $H$. We define $s-L i_{n} C_{n}$ and $w-L s_{n} C_{n}$ as follows.
(i) $x \in s-L i_{n} C_{n}$ if and only if there exists $\left\{x_{n}\right\} \subset C_{n}$ such that $x_{n} \rightarrow x$.
(ii) $x \in w-L s_{n} C_{n}$ if and only if there exist a subsequence $\left\{C_{n_{i}}\right\}$ of $\left\{C_{n}\right\}$ and a sequence $\left\{y_{i}\right\}$ in $C_{n_{i}}$ such that $y_{i} \rightharpoonup y$.
If $C_{0}$ satisfies the following:

$$
C_{0}=s-L i_{n} C_{n}=w-L s_{n} C_{n}
$$

then we say that $\left\{C_{n}\right\}$ converges to $C_{0}$ in the sense of Mosco [10] and we write $C_{0}=M-\lim _{n \rightarrow \infty} C_{n}$. It is easy to show that, if $\left\{C_{n}\right\}$ is nonincreasing with respect to inclusion, then $\left\{C_{n}\right\}$ converges to $\bigcap_{n=1}^{\infty} C_{n}$ in the sense of Mosco.

Tsukada [13] proved the following theorem for the metric projection:
Lemma 2.3 ([13]). Let $\left\{C_{n}\right\}$ be a sequence of nonempty closed convex subsets of a Hilbert space $H$. If $C_{0}=M-\lim _{n \rightarrow \infty} C_{n}$ exists and is nonempty, then, for each $x \in H,\left\{\operatorname{proj}_{C_{n}}(x)\right\}$ converges strongly to $\operatorname{proj}_{C_{0}}(x)$, where $\operatorname{proj}_{C_{n}}$ and proj$C_{0}$ are the metric projections of $H$ onto $C_{n}$ and $C_{0}$, respectively.

Let $(X, d)$ be a complete metric space. A mapping $f: X \rightarrow X$ is called a Meir-Keeler contraction ([9]) if, for any $\epsilon>0$, there exists $\delta>0$ such that

$$
d(x, y)<\epsilon+\delta \Longrightarrow d(f(x), f(y))<\epsilon, \forall x, y \in X
$$

It is well known that the Meir-Keeler contraction is a generalization of the contraction.

Lemma 2.4 ([9]). A Meir-Keeler contraction defined on a complete metric space has a unique fixed point.

Lemma 2.5 ([12]). Let $f$ be a Meir-Keeler contraction on a convex subset $C$ of $a$ Banach space E. Then, for any $\epsilon>0$, there exists $r \in(0,1)$ such that

$$
\|x-y\| \geq \epsilon \Longrightarrow\|f(x)-f(y)\| \leq r\|x-y\|
$$

for all $x, y \in C$.
Lemma 2.6 ([12]). Let $C$ be a convex subset of a Banach space $E$. Let $T$ be $a$ nonexpansive mapping on $C$ and $f$ be a Meir-Keeler contraction on $C$. Then the following hold:
(i) $T f$ is a Meir-Keeler contraction on $C$.
(ii) For each $\alpha \in(0,1),(1-\alpha) T+\alpha f$ is a Meir-Keeler contraction on $C$.

## 3. Main Results

First, we suggest a shrinking projection algorithm for finding the common element of variational inequality problem and fixed point problem. Subsequently, we show the strong convergence of the presented algorithm.

Algorithm 3.1. Let $C$ be a nonempty closed convex subset of a real Hilbert space $H$. Let $f: C \rightarrow C$ be a Meir-Keeler contractive operator and $A: C \rightarrow H$ be a $\delta$-inverse strongly monotone operator. Let $T: C \rightarrow C$ be an L-Lipschitz pseudocontractive operator with $L>1$. For $x_{0} \in C_{0}=C$ arbitrarily, define a sequence $\left\{x_{n}\right\}$ iteratively by

$$
\left\{\begin{array}{l}
z_{n}=\operatorname{proj}_{C}\left(x_{n}-\lambda_{n} A x_{n}\right)  \tag{3.1}\\
y_{n}=\left(1-\alpha_{n}\right) z_{n}+\alpha_{n} T\left(\left(1-\beta_{n}\right) z_{n}+\beta_{n} T z_{n}\right) \\
C_{n+1}=\left\{z \in C_{n}:\left\|y_{n}-z\right\| \leq\left\|x_{n}-z\right\|\right\} \\
x_{n+1}=\operatorname{proj}_{C_{n+1}} f\left(x_{n}\right), n \geq 0,
\end{array}\right.
$$

where $\left\{\lambda_{n}\right\} \subset[a, b] \subset(0,2 \delta),\left\{\alpha_{n}\right\} \subset(0,1)$ and $\left\{\beta_{n}\right\} \subset(0,1)$.
Set $\Omega:=V I(A, C) \cap \operatorname{Fix}(T)$. Suppose $\Omega \neq \emptyset$. Since $f$ is a Meir-Keeler contraction of $C$, it follows that $\operatorname{proj}_{\Omega} f$ is a Meir-Keeler contraction of $C$ by Lemma 2.6. According to Lemma 2.4, there exists a unique fixed point $x^{\dagger} \in C$ such that $x^{\dagger}=\operatorname{proj}_{\Omega} f\left(x^{\dagger}\right)$.

Conclusion 3.2. $\Omega \subset C_{n}$ for all $n \geq 0$
Proof. In fact, $\Omega \subset C_{0}$ is obvious. Suppose that $\Omega \subset C_{k}$ for some $k \in \mathbb{N}$. Set $v_{n}=\left(1-\beta_{n}\right) z_{n}+\beta_{n} T z_{n}$ for all $n \geq 0$. Then $y_{n}=\left(1-\alpha_{n}\right) z_{n}+\alpha_{n} T v_{n}$ for all $n \geq 0$. Let $x^{*} \in \Omega \subset C_{k}$. Then, we have

$$
\begin{align*}
\left\|z_{n}-x^{*}\right\| & =\left\|\operatorname{proj}_{C}\left(x_{n}-\lambda_{n} A x_{n}\right)-\operatorname{proj}_{C}\left(x^{*}-\lambda_{n} A x^{*}\right)\right\| \\
& \leq\left\|\left(x_{n}-\lambda_{n} A x_{n}\right)-\left(x^{*}-\lambda_{n} A x^{*}\right)\right\|  \tag{3.2}\\
& \leq\left\|x_{n}-x^{*}\right\| .
\end{align*}
$$

By Lemma 2.2 and (3.2), we have

$$
\begin{align*}
\left\|y_{n}-x^{*}\right\| & =\left\|\left(1-\alpha_{n}\right) z_{n}+\alpha_{n} T\left(\left(1-\beta_{n}\right) z_{n}+\beta_{n} T z_{n}\right)-x^{*}\right\| \\
& \leq\left\|z_{n}-x^{*}\right\|  \tag{3.3}\\
& \leq\left\|x_{n}-x^{*}\right\|
\end{align*}
$$

and hence $x^{*} \in C_{k+1}$. This indicates that $\Omega \subset C_{n}$ for all $n \geq 0$.
Conclusion 3.3. $C_{n}$ is closed and convex for all $n \geq 0$.
Proof. In fact, it is obvious from the assumption that $C_{0}=C$ is closed convex. Suppose that $C_{k}$ is closed and convex for some $k \in \mathbb{N}$. For any $z \in C_{k},\left\|y_{k}-z\right\| \leq$ $\left\|x_{k}-z\right\|$ is equivalent to

$$
\left\|y_{k}-x_{k}\right\|^{2}+2\left\langle y_{k}-x_{k}, x_{k}-z\right\rangle \leq 0 .
$$

So $C_{k+1}$ is closed and convex. By induction, we deduce that $C_{n}$ is closed and convex for all $n \geq 0$.

Remark 3.4. By Conclusions 3.2 and 3.3, we deduce that $\left\{x_{n}\right\}$ is well-defined. Since $\bigcap_{n=1}^{\infty} C_{n}$ is closed convex, we also have that $\operatorname{proj}_{\cap_{n=1}^{\infty} C_{n}}$ is well-defined and so $\operatorname{proj}_{\cap_{n=1}^{\infty} C_{n}} f$ is a Meir-Keeler contraction on $C$. By Lemma 2.4, there exists a unique fixed point $u \in \bigcap_{n=1}^{\infty} C_{n}$ of $\operatorname{proj}_{\bigcap_{n=1}^{\infty} C_{n}} f$. Since $C_{n}$ is a nonincreasing sequence of nonempty closed convex subsets of $H$ with respect to inclusion, it follow that

$$
\emptyset \neq \Omega \subset \bigcap_{n=1}^{\infty} C_{n}=M-\lim _{n \rightarrow \infty} C_{n}
$$

Setting $u_{n}:=\operatorname{proj}_{C_{n}} f(u)$ and applying Lemma 2.3, we can conclude that

$$
\lim _{n \rightarrow \infty} u_{n}=\operatorname{proj}_{\bigcap_{n=1}^{\infty} C_{n}} f(u)=u
$$

Conclusion 3.5. $\lim _{n \rightarrow \infty}\left\|x_{n}-u\right\|=0$
Proof. Assume that $M=\lim \sup _{n \rightarrow \infty}\left\|x_{n}-u\right\|>0$. Then, for any $\epsilon$ with $0<\epsilon<M$, we can choose $\delta_{1}>0$ such that

$$
\begin{equation*}
\limsup _{n \rightarrow \infty}\left\|x_{n}-u\right\|>\epsilon+\delta_{1} \tag{3.4}
\end{equation*}
$$

Since $f$ is a Meir-Keeler contraction, for the positive $\epsilon$, there exists another $\delta_{2}>0$ such that

$$
\begin{equation*}
\|x-y\|<\epsilon+\delta_{2} \Longrightarrow\|f(x)-f(y)\|<\epsilon \tag{3.5}
\end{equation*}
$$

for all $x, y \in C$.
In fact, we can choose a common $\delta>0$ such that (3.4) and (3.5) hold. If $\delta_{1}>\delta_{2}$, then

$$
\limsup _{n \rightarrow \infty}\left\|x_{n}-u\right\|>\epsilon+\delta_{1}>\epsilon+\delta_{2}
$$

If $\delta_{1} \leq \delta_{2}$, then, from (3.5), it follows that

$$
\|x-y\|<\epsilon+\delta_{1} \Longrightarrow\|f(x)-f(y)\|<\epsilon
$$

for all $x, y \in C$. Thus we have

$$
\begin{equation*}
\limsup _{n \rightarrow \infty}\left\|x_{n}-u\right\|>\epsilon+\delta \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\|x-y\|<\epsilon+\delta \Longrightarrow\|f(x)-f(y)\|<\epsilon \tag{3.7}
\end{equation*}
$$

for all $x, y \in C$. Since $u_{n} \rightarrow u$, there exists $n_{0} \in \mathbb{N}$ such that

$$
\begin{equation*}
\left\|u_{n}-u\right\|<\delta \tag{3.8}
\end{equation*}
$$

for all $n \geq n_{0}$.
Now, we now consider two possible cases:
Case 1. There exists $n_{1} \geq n_{0}$ such that

$$
\left\|x_{n_{1}}-u\right\| \leq \epsilon+\delta
$$

By (3.7) and (3.8), we get

$$
\begin{aligned}
\left\|x_{n_{1}+1}-u\right\| & \leq\left\|x_{n_{1}+1}-u_{n_{1}+1}\right\|+\left\|u_{n_{1}+1}-u\right\| \\
& =\left\|\operatorname{proj}_{C_{n_{1}+1}} f\left(x_{n_{1}}\right)-\operatorname{proj}_{C_{n_{1}+1}} f(u)\right\|+\left\|u_{n_{1}+1}-u\right\| \\
& \leq\left\|f\left(x_{n_{1}}\right)-f(u)\right\|+\left\|u_{n_{1}+1}-u\right\| \\
& \leq \epsilon+\delta
\end{aligned}
$$

By induction, we can obtain that

$$
\left\|x_{n_{1}+m}-u\right\| \leq \epsilon+\delta
$$

for all $m \geq 1$, which implies that

$$
\limsup _{n \rightarrow \infty}\left\|x_{n}-u\right\| \leq \epsilon+\delta
$$

which contradicts (3.6). Therefore, we conclude that $\left\|x_{n}-u\right\| \rightarrow 0$ as $n \rightarrow \infty$.
Case 2. $\left\|x_{n}-u\right\|>\epsilon+\delta$ for all $n \geq n_{0}$.
Now, we prove that Case 2 is impossible. Suppose that Case 2 is true. By Lemma 2.5 , there exists $r \in(0,1)$ such that

$$
\left\|f\left(x_{n}\right)-f(u)\right\| \leq r\left\|x_{n}-u\right\|
$$

for all $n \geq n_{0}$. Thus we have

$$
\begin{aligned}
\left\|x_{n+1}-u_{n+1}\right\| & =\left\|\operatorname{proj}_{C_{n+1}} f\left(x_{n}\right)-\operatorname{proj}_{C_{n+1}} f(u)\right\| \\
& \leq\left\|f\left(x_{n}\right)-f(u)\right\| \\
& \leq r\left\|x_{n}-u\right\|
\end{aligned}
$$

for all $n \geq n_{0}$. It follows that

$$
\begin{aligned}
\lim _{n \rightarrow \infty}\left\|x_{n+1}-u\right\| & =\limsup _{n \rightarrow \infty}\left\|x_{n+1}-u_{n+1}\right\| \\
& \leq r \limsup _{n \rightarrow \infty}\left\|x_{n}-u\right\| \\
& <\limsup _{n \rightarrow \infty}\left\|x_{n}-u\right\|
\end{aligned}
$$

which gives a contradiction. Hence we obtain

$$
\lim _{n \rightarrow \infty}\left\|x_{n}-u\right\|=0
$$

Theorem 3.6. If $0<c<\alpha_{n} \leq \beta_{n}<d<\frac{1}{\sqrt{1+L^{2}+1}}$, then the sequence $\left\{x_{n}\right\}$ defined by (3.1) converges strongly to $x^{\dagger}$.

Proof. By Conclusion 3.5, we get that $\left\{x_{n}\right\}$ is bounded. Observe that

$$
\begin{aligned}
\left\|x_{n+1}-x_{n}\right\| & \leq\left\|x_{n}-u\right\|+\left\|u-u_{n+1}\right\|+\left\|u_{n+1}-x_{n+1}\right\| \\
& =\left\|x_{n}-u\right\|+\left\|u-u_{n+1}\right\|+\left\|\operatorname{proj}_{C_{n+1}} f\left(x_{n}\right)-\operatorname{proj}_{C_{n+1}} f(u)\right\| \\
& \leq\left\|x_{n}-u\right\|+\left\|u-u_{n+1}\right\|+\left\|f\left(x_{n}\right)-f(u)\right\|
\end{aligned}
$$

Therefore, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n+1}-x_{n}\right\|=0 \tag{3.9}
\end{equation*}
$$

Since $x_{n+1} \in C_{n+1}$, we have

$$
\left\|y_{n}-x_{n+1}\right\| \leq\left\|x_{n}-x_{n+1}\right\|
$$

This together with (3.9) implies that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-x_{n+1}\right\|=\lim _{n \rightarrow \infty}\left\|y_{n}-x_{n}\right\|=0 \tag{3.10}
\end{equation*}
$$

Note that

$$
\begin{aligned}
\left\|y_{n}-x^{*}\right\|^{2} & \leq\left\|z_{n}-x^{*}\right\|^{2} \\
& \leq\left\|\left(x_{n}-\lambda_{n} A x_{n}\right)-\left(x^{*}-\lambda_{n} A x^{*}\right)\right\|^{2} \\
& =\left\|x_{n}-x^{*}\right\|^{2}+\lambda_{n}^{2}\left\|A x_{n}-A x^{*}\right\|^{2}-2\left\langle A x_{n}-A x^{*}, x_{n}-x^{*}\right\rangle \\
& =\left\|x_{n}-x^{*}\right\|^{2}+\lambda_{n}\left(\lambda_{n}-2 \delta\right)\left\|A x_{n}-A x^{*}\right\|^{2} \\
& \leq\left\|x_{n}-x^{*}\right\|^{2}+(b-2 \delta) b\left\|A x_{n}-A x^{*}\right\|^{2} .
\end{aligned}
$$

Then we have

$$
\begin{align*}
(2 \delta-b) b\left\|A x_{n}-A x^{*}\right\|^{2} & \leq\left\|x_{n}-x^{*}\right\|^{2}-\left\|y_{n}-x^{*}\right\|^{2}  \tag{3.12}\\
& \leq\left\|x_{n}-y_{n}\right\|\left(\left\|x_{n}-x^{*}\right\|+\left\|y_{n}-x^{*}\right\|\right)
\end{align*}
$$

By (3.10) and (3.12), we obtain

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|A x_{n}-A x^{*}\right\|=0 \tag{3.13}
\end{equation*}
$$

Since $\operatorname{proj}_{C}$ is firmly-nonexpansive, we have

$$
\begin{aligned}
\left\|z_{n}-x^{*}\right\|^{2}= & \left\|\operatorname{proj}_{C}\left(x_{n}-\lambda_{n} A x_{n}\right)-\operatorname{proj}_{C}\left(x^{*}-\lambda_{n} A x^{*}\right)\right\|^{2} \\
\leq \leq & \left\langle\left(x_{n}-\lambda_{n} A x_{n}\right)-\left(x^{*}-\lambda_{n} A x^{*}\right), z_{n}-x^{*}\right\rangle \\
= & \frac{1}{2}\left(\left\|\left(x_{n}-\lambda_{n} A x_{n}\right)-\left(x^{*}-\lambda_{n} A x^{*}\right)\right\|^{2}+\left\|z_{n}-x^{*}\right\|^{2}\right. \\
& \left.-\left\|\left(x_{n}-\lambda_{n} A x_{n}\right)-\left(x^{*}-\lambda_{n} A x^{*}\right)+x^{*}-z_{n}\right\|^{2}\right) \\
\leq & \frac{1}{2}\left(\left\|x_{n}-x^{*}\right\|^{2}+\left\|z_{n}-x^{*}\right\|^{2}-\left\|\left(x_{n}-z_{n}\right)-\lambda_{n}\left(A x_{n}-A x^{*}\right)\right\|^{2}\right) \\
= & \frac{1}{2}\left(\left\|x_{n}-x^{*}\right\|^{2}+\left\|z_{n}-x^{*}\right\|^{2}-\left\|x_{n}-z_{n}\right\|^{2}\right. \\
& \left.+2 \lambda_{n}\left\langle x_{n}-z_{n}, A x_{n}-A x^{*}\right\rangle-\lambda_{n}^{2}\left\|A x_{n}-A x^{*}\right\|^{2}\right)
\end{aligned}
$$

It follows that

$$
\begin{align*}
\left\|z_{n}-x^{*}\right\|^{2} \leq & \left\|x_{n}-x^{*}\right\|^{2}+2 \lambda_{n}\left\langle x_{n}-z_{n}, A x_{n}-A x^{*}\right\rangle  \tag{3.15}\\
& -\left\|x_{n}-z_{n}\right\|^{2}-\lambda_{n}^{2}\left\|A x_{n}-A x^{*}\right\|^{2}
\end{align*}
$$

From (3.3) and (3.15), we get

$$
\begin{aligned}
\left\|y_{n}-x^{*}\right\|^{2} \leq & \left\|z_{n}-x^{*}\right\|^{2} \\
\leq & \left\|x_{n}-x^{*}\right\|^{2}-\left\|x_{n}-z_{n}\right\|^{2}+2 \lambda_{n}\left\langle x_{n}-z_{n}, A x_{n}-A x^{*}\right\rangle \\
& -\lambda_{n}^{2}\left\|A x_{n}-A x^{*}\right\|^{2} \\
\leq & \left\|x_{n}-x^{*}\right\|^{2}-\left\|x_{n}-z_{n}\right\|^{2}+2 \lambda_{n}\left\|x_{n}-z_{n}\right\|\left\|A x_{n}-A x^{*}\right\|
\end{aligned}
$$

and so

$$
\begin{aligned}
\left\|x_{n}-z_{n}\right\|^{2} & \leq\left\|x_{n}-x^{*}\right\|^{2}-\left\|y_{n}-x^{*}\right\|^{2}+2 \lambda_{n}\left\|x_{n}-z_{n}\right\|\left\|A x_{n}-A x^{*}\right\| \\
& \leq\left\|x_{n}-y_{n}\right\|\left(\left\|x_{n}-x^{*}\right\|+\left\|y_{n}-x^{*}\right\|\right)+2 \lambda_{n}\left\|x_{n}-z_{n}\right\|\left\|A x_{n}-A x^{*}\right\| .
\end{aligned}
$$

This together with (3.10) and (3.13) implies that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n}-z_{n}\right\|=0 \tag{3.16}
\end{equation*}
$$

Next, we prove that $u \in \operatorname{Fix}(T) \cap V I(A, C)$. Note that

$$
\begin{aligned}
\left\|z_{n}-T z_{n}\right\| & \leq\left\|z_{n}-y_{n}\right\|+\left\|y_{n}-T z_{n}\right\| \\
& \leq\left\|z_{n}-y_{n}\right\|+\left(1-\alpha_{n}\right)\left\|z_{n}-T z_{n}\right\|+\alpha_{n}\left\|T v_{n}-T z_{n}\right\| \\
& \leq\left\|z_{n}-y_{n}\right\|+\left(1-\alpha_{n}\right)\left\|z_{n}-T z_{n}\right\|+\alpha_{n} L\left\|v_{n}-z_{n}\right\| \\
& \leq\left\|z_{n}-y_{n}\right\|+\left(1-\alpha_{n}\right)\left\|z_{n}-T z_{n}\right\|+\alpha_{n} \beta_{n} L\left\|z_{n}-T z_{n}\right\| .
\end{aligned}
$$

It follows that

$$
\begin{equation*}
\left\|z_{n}-T z_{n}\right\| \leq \frac{1}{\alpha_{n}\left(1-\beta_{n} L\right)}\left\|z_{n}-y_{n}\right\| \leq \frac{1}{c(1-d L)}\left\|z_{n}-y_{n}\right\| \rightarrow 0 . \tag{3.17}
\end{equation*}
$$

Since $x_{n} \rightarrow u$, we have $z_{n} \rightarrow u$ by (3.16). So, from (3.17) and Lemma 2.1, we deduce that $u \in \operatorname{Fix}(T)$. By the same argument as that in the proof of $[4$, Theorem 3.1], we can show that $u \in V I(A, C)$. This implies that $u \in V I(A, C)$. Therefore, we have $u \in \Omega$. Since $x_{n+1}=\operatorname{proj}_{C_{n+1}} f\left(x_{n}\right)$, we have

$$
\left\langle f\left(x_{n}\right)-x_{n+1}, x_{n+1}-y\right\rangle \geq 0
$$

for all $y \in C_{n+1}$. Since $\Omega \subset C_{n+1}$, we get

$$
\left\langle f\left(x_{n}\right)-x_{n+1}, x_{n+1}-y\right\rangle \geq 0
$$

for all $y \in \Omega$. Noting that $x_{n} \rightarrow u \in \Omega$, we deduce

$$
\langle f(u)-u, u-y\rangle \geq 0
$$

for all $y \in \Omega$. Thus $u=\operatorname{proj}_{\Omega} f(u)=x^{\dagger}$. This completes the proof.

## References

[1] E. Blum and W. Oettli, From optimization and variational inequalities to equilibrium problems, Math. Stud. 63 (1994), 123-145.
[2] L. C. Ceng, A. Petrusel and J.C. Yao, Strong convergence of modified implicit iterative algorithms with perturbed mappings for continuous pseudocontractive mappings, Applied Math. Comput. 209 (2009), 162-176.
[3] L. Ciric, A. Rafiq, Nenad Cakic and J.S. Ume, Implicit Mann fixed point iterations for pseudocontractive mappings, Appl. Math. Let. 22 (2009), 581-584.
[4] J. W. Chen, E. Kobis, M. A. Kobis and J. C. Yao, Optimality conditions for solutions of constrained inverse vector variational inequalities by means of nonlinear scalarization, J. Nonlinear Var. Anal. 1 (2017), 145-158.
[5] H. Iiduka and W. Takahashi, Weak convergence of a projection algorithm for variational inequalities in a Banach space, J. Math. Anal. Appl. 339 (2008), 668-679.
[6] H. Iiduka, W. Takahashi and M. Toyoda, Approximation of solutions of variational inequalities for monotone mappings, Panamerican Math. J. 14 (2004), 49-61.
[7] A. N. Iusem, An iterative algorithm for the variational inequality problem, Comput. Appl. Math. 13 (1994), 103-114.
[8] G. M. Korpelevich, An extragradient method for finding saddle points and for other problems, Ekonomika i Matematicheskie Metody 12 (1976), 747-756.
[9] A. Meir and E. Keeler, A theorem on contraction mappings, J. Math. Anal. Appl. 28 (1969), 326-329.
[10] U. Mosco, Convergence of convex sets and of solutions of variational inequalities, Advances in Math. 3 (1969), 510-585.
[11] G. Stampacchia, Formes bilineaires coercitives sur les ensembles convexes, C.R. Acad. Sci. Paris 258 (1964), 4413-4416.
[12] T. Suzuki, Moudafi's viscosity approximations with Meir-Keeler contractions, J. Math. Anal. Appl. 325 (2007), 342-352.
[13] M. Tsukada, Convergence of best approximations in a smooth Banach space, J. Approx. Theory 40 (1984), 301-309.
[14] Y. H. Yao, Y. C. Liou and J. C. Yao, Iterative algorithms for the split variational inequality and fixed point problems under nonlinear transformations, J. Nonlinear Sci. Appl. 10 (2017), 843-854.
[15] Y. H. Yao and N. Shahzad, An algorithmic approach to the split variational inequality and fixed point problem, J. Nonlinear Convex Anal. 18 (2017), 977-991.
[16] L. J. Lin and W. Takahashi, A general iterative method for hierarchical variational inequality problems in Hilbert spaces and applications, Positivity 16 (2012), 429-453.
[17] N. Nadezhkina and W. Takahashi, Strong convergence theorem by a hybrid method for nonexpansive mappings and Lipschitz-continuous monotone mappings, SIAM J. Optim. 16 (2006), 1230-1241.
[18] Y. H. Yao, Y. C. Liou, J. C. Yao, Split common fixed point problem for two quasipseudocontractive operators and its algorithm construction, Fixed Point Theory Appl. 2015 (2015), Art. ID 127.
[19] Y. H. Yao and M. Postolache, Projection methods for firmly type nonexpansive operators, J. Nonlinear Convex Anal. in press.
[20] H. Zegeye, N. Shahzad and T. Mekonen, Viscosity approximation methods for pseudocontractive mappings in Banach spaces, Appl. Math. Comput. 185 (2007), 538-546.
[21] H. Zegeye, N. Shahzad and Y. H. Yao, Minimum-norm solution of variational inequality and fixed point problem in Banach spaces, Optim. 64 (2015), 453-471.
[22] H. Zhou, Convergence theorems of fixed points for Lipschitz pseudocontractions in Hilbert spaces, J. Math. Anal. Appl. 343 (2008), 546-556.

Manuscript received 26 October 2017

## Y. H. YAO

Department of Mathematics, Tianjin Polytechnic University, Tianjin 300387, China
E-mail address: yaoyonghong@aliyun.com


[^0]:    2010 Mathematics Subject Classification. 47J20, 47H09, 65J15.
    Key words and phrases. Variational inequality, fixed point, Shrinking projection, Meir-Keeler contraction.

