

NEW RESULTS ON THE PROPERTIES OF SOLUTIONS OF A CAPUTO FRACTIONAL DIFFERENTIAL SYSTEM

OSMAN TUNÇ, CEMIL TUNÇ, AND CHING-FENG WEN*

ABSTRACT. This paper considers a perturbed nonlinear system of fractional ordinary differential equations (FrODEs) with Caputo fractional derivative. The aim of paper is to study uniform stability, asymptotic stability, Mittag-Leffer stability of zero solution as well as boundedness of non-zero solutions of this system of FrODEs with Caputo fractional derivative. We obtain four new theorems on these mathematical concepts by applying the second Lyapunov method. In order to explain the obtained results and show their applications, an example is given, which satisfies the constructed conditions. The results of this paper extend some results that can be found in the literature and they have contributions to theory of FrODEs.

1. INTRODUCTION

As we all know from fractional calculus, traditional definitions of integral and derivative of a function are generalized from integer orders to real orders. Hence, together with order differential equations, numerous forms of fractional order differential equations raised in the relevant literature. During the past decades, qualitative behaviors of fractional order ordinary differentials have been paid more and more attentions due to their significant applications in sciences and engineering. From the relevant literature, it follows that, in recent years, different and the same kind of qualitative problems for various scalar FrODEs and systems of FrODEs with Caputo fractional derivative of the form

$${}^C D_t^q x(t) = A(t)x(t),$$

$${}^C D_t^q x(t) = f(t, x(t)), \quad x(t_0) = x_0, \quad f(t, 0) = 0,$$

and numerous others forms of these FrODEs have been investigated and are still being investigated by many authors (see, for example, [1], [2], [4-7], [9-11], [13-17], [27-33] and the references of these sources). Today, continuing investigations on various problems in qualitative theory of FrODEs is a very attractive topic in the literature due to effective roles of FrODEs in sciences and engineering. Therefore, it deserves to investigate behaviors of solutions of FrODEs with Caputo fractional derivative.

In this paper, motivated by the recent literature on qualitative theory of FrODEs, we study a nonlinear perturbed system of FrODEs of Caputo type

$$(1.1) \quad {}^C D_t^q x(t) = -A(t)x(t) - f(t, x(t)) + g(t, x(t)),$$

2010 *Mathematics Subject Classification.* 34D05, 34K20, 45J05.

Key words and phrases. Fractional differential system, uniform stability, asymptotic stability, Mittag-Leffer stability, boundedness, Lyapunov function (LF) .

*Corresponding author.

where $x = (x_1, \dots, x_n)^T \in \mathbb{R}^n$, $t \in \mathbb{R}^+$, $\mathbb{R}^+ = [0, \infty)$, $q \in (0, 1)$, $A(t) = (a_{ij}(t)) \in C(\mathbb{R}^+, \mathbb{R}^{n \times n})$, $A(t)$ is a symmetric matrix, $(i, j = 1, \dots, n)$, $f = (f_1, \dots, f_n)^T \in C(\mathbb{R}^+ \times \mathbb{R}^n, \mathbb{R}^n)$, $f_i(t, x(t)) = f_i(t, x_1(t), \dots, x_n(t))$, $f(t, 0) = 0$, $g = (g_1, \dots, g_n)^T \in C(\mathbb{R}^+ \times \mathbb{R}^n, \mathbb{R}^n)$, $g_i(t, x(t)) = g_i(t, x_1(t), \dots, x_n(t))$ and $g(t, 0) = 0$. Then, the system of FrODEs (1.1) with Caputo derivative includes the zero solution.

The motivation to consider the perturbed system of FrODEs (1.1) and to study the mentioned qualitative concepts comes from the books ([3], [6], [11], [15], [16], [33]), the papers ([1], [2],[4],[5],[7-10], [12-14], [17-32]) and the references of these sources. Here, our aim is to obtain some new results on the uniform stability, asymptotic stability, Mittag-Leffler stability of zero solution of system of FrODEs (1.1) as well as boundedness of solutions of non-zero solutions of system of FrODEs (1.1) using the second Lyapunov method and Caputo derivative. The main results of this paper are new, original and they have contributions to the qualitative theory of FrODEs with Caputo derivatives.

2. BASIC RESULTS

We now consider a system of FrODEs with a Caputo derivative:

$$(2.1) \quad {}^C_{t_0}D_t^q x(t) = F(t, x(t)),$$

where $q \in (0, 1)$, $F(t, 0) = 0$, $F \in C(\mathbb{R}^+ \times \mathbb{R}^n, \mathbb{R}^n)$ and $\mathbb{R}^+ = [0, \infty)$. The following basis results and concepts are needed in the remainder of this paper.

Definition 2.1. ([13]). *A continuous function $\gamma_1 : [0, t) \rightarrow [0, +\infty)$ is said to belong to class-K if it is strictly increasing and $\gamma_1(0) = 0$.*

Theorem 2.1. ([7]). *Let $x = 0$ be an equilibrium point for the non-autonomous system of FrODEs (2.1). Let us assume that there exist a continuous Lyapunov function $V(t, x(t))$ and a scalar class-K function $\gamma_1(\cdot)$ such that, $\forall x \neq 0$,*

$$\gamma_1(\|x(t)\|) \leq V(t, x(t)),$$

and

$${}^C_{t_0}D_t^q V(t, x(t)) \leq 0 \text{ with } q \in (0, 1).$$

Then the origin of the system of FrODEs (2.1) is Lyapunov stable.

If, furthermore, there is a scalar class-K function $\gamma_2(\cdot)$ satisfying

$$V(t, x(t)) \leq \gamma_2(\|x(t)\|)$$

then the origin of the system of FrODEs (2.1) is Lyapunov uniformly stable.

Theorem 2.2. ([13]). *Let $x = 0$ be an equilibrium point for the non-autonomous system of FrODEs (2.1). Assume that there exist a Lyapunov function $V(t, x(t))$ and class-K functions γ_i ($i = 1, 2, 3$) satisfying*

$$\gamma_1(\|x\|) \leq V(t, x) \leq \gamma_2(\|x\|),$$

$${}^C_{t_0}D_t^q V(t, x(t)) \leq -\gamma_3(\|x\|),$$

where $q \in (0, 1)$. Then the system of FrODEs (2.1) is asymptotically stable.

Definition 2.2. ([14]). *The trivial solution of the system of FrODEs (2.1) is said to be Mittag-Leffler stable if*

$$\|x(t)\| \leq [m(x(t_0))E_v(-\sigma(t - t_0)^v)]^\mu,$$

where $v \in (0, 1]$, $\sigma \geq 0$, $\mu > 0$, $m(0) = 0$, $m(x) \geq 0$, $m(x)$ is locally Lipschitz with Lipschitz constant m_0 , and

$$E_v(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(vk + 1)}$$

is the one-parameter Mittag-Leffler function, and Γ denotes the Gamma function.

Lemma 2.1. ([14]). *Let $x \in \mathbb{R}^n$ be a vector of differentiable functions. If a continuous function $V : [t_0, \infty) \times \mathbb{R}^n \rightarrow \mathbb{R}^+$ satisfies*

$${}^C_{t_0}D_t^q V(t, x(t)) \leq -\alpha V(t, x(t)),$$

then

$$V(t, x(t)) \leq V(t_0, x(t_0))E_q(-\alpha(t - t_0)^q),$$

where $\alpha > 0$ and $0 < q < 1$.

Lemma 2.2. ([16]).

$${}^C_{t_0}D_t^q(ax(t) + by(t)) = a {}^C_{t_0}D_t^q x(t) + b {}^C_{t_0}D_t^q y(t),$$

where $q \in (0, 1]$.

Let $x \in \mathbb{R}^n$ and $M \in \mathbb{R}^{n \times n}$. In this paper, the vector and matrix norms are defined by $\|x\| = \left(\sum_{i=1}^n |x_i|\right)$ and $\|M\| = \max_{1 \leq j \leq n} \left(\sum_{i=1}^n |m_{ij}|\right)$, respectively. We will use the definitions of both of these norms, when it is needed.

3. ANALYSES OF BEHAVIORS OF SOLUTIONS

We will use the following conditions in our main results.

(C1) There is a positive constant ρ_0 such that

$$a_{ii}(t) - \sum_{j=1, j \neq i}^n |a_{ji}(t)| > \rho_0, t \in \mathbb{R}^+.$$

(C2)

$$f(t, 0) = g(t, 0) = 0,$$

$$x_i(t)f_i(t, x(t)) > 0, (x_i(t) \neq 0), \text{ for all } t \in \mathbb{R}^+ \text{ and all } x \in \mathbb{R}^n.$$

(C3) There is a positive constant ρ_0 from (C1) such that

$$\rho_0 \|x(t)\| + \|f(t, x(t))\| - \|g(t, x(t))\| \geq 0 \text{ for all } t \in \mathbb{R}^+ \text{ and all } x \in \mathbb{R}^n.$$

(C4) There are positive constants ρ_0 from (C1), f_0 , g_0 and ρ_2 such that

$$\|f(t, x(t))\| \geq f_0 \|x(t)\|,$$

$$\|g(x(t))\| \leq g_0 \|x(t)\| \text{ for all } t \in \mathbb{R}^+ \text{ and } x \in \mathbb{R}^n,$$

and

$$\rho_0 + f_0 - g_0 \geq \rho_2.$$

Our first result, Theorem 3.1, studies the uniformly stability of the zero solution of the system of FrODEs (1.1).

Theorem 3.1. *The zero solution of the system of FrODEs (1.1) is uniformly stable if conditions (C1)-(C3) are satisfied.*

Proof. We define a LF $\Xi := \Xi(t, x(t))$ by

$$(3.1) \quad \Xi(t, x(t)) := \|x(t)\| = \sum_{i=1}^n |x_i(t)| = |x_1(t)| + \dots + |x_n(t)|.$$

From this point, it is clear that the LF $\Xi(t, x(t))$ in (3.1) satisfies the following relations:

$$\Xi(t, 0) = 0, k_1 |x_1(t)| + \dots + k_1 |x_n(t)| = k_1 \|x\| \leq \Xi(t, x(t)),$$

and

$$\Xi(t, x(t)) \leq k_2 |x_1(t)| + \dots + k_2 |x_n(t)| = k_2 \|x(t)\|,$$

i.e., we have

$$k_1 \|x\| \leq \Xi(t, x(t)) \leq k_2 \|x\|,$$

where $k_1 \in (0, 1)$ and $k_2 \geq 1$.

Calculating the Caputo fractional derivative of the LF $\Xi(t, x(t))$ in (3.1) along the system of FrODEs (1.1), using conditions (C1), (C2) and elementary calculations, we obtain

$$\begin{aligned} {}^C_{t_0} D_t^q \Xi(t, x(t)) &= {}^C_{t_0} D_t^q \Xi \|x(t)\| \\ &= {}^C_{t_0} D_t^q (|x_1(t)| + \dots + |x_n(t)|) \\ &= {}^C_{t_0} D_t^q |x_1(t)| + \dots + {}^C_{t_0} D_t^q |x_n(t)| \\ &= \sum_{i=1}^n x'_i(t) \operatorname{sgn} x_i(t+0) \\ &= {}^C_{t_0} D_t^q x_1(t) [\operatorname{sgn} x_1(t+0)] + \dots + {}^C_{t_0} D_t^q x_n(t) [\operatorname{sgn} x_n(t+0)] \\ &= - \sum_{i=1}^n [(a_{ii}(t)x_i(t)) \times \operatorname{sgn} x_i(t+0)] \end{aligned}$$

$$\begin{aligned}
 & - \sum_{i=1}^n \sum_{j=1, i \neq j}^n a_{ji}(t)x_i \times \operatorname{sgn}x_i(t+0) \\
 & - \sum_{i=1}^n [f_i(t, x(t)) - g_i(t, x(t))] \times \operatorname{sgn}x_i(t+0) \\
 \leq & - \sum_{i=1}^n \left[a_{ii}(t) - \sum_{j=1, j \neq i}^n |a_{ji}(t)| \right] |x_i(t)| \\
 & - \|f(t, x(t))\| + \|g(t, x(t))\| \\
 = & - \left[\sum_{i=1}^n a_{ii}(t) - \sum_{j=1, j \neq i}^n |a_{ji}(t)| \right] |x_i| \\
 & - \|f(t, x(t))\| + \|g(t, x(t))\| \\
 \leq & - \rho_0 \|x\| - \|f(t, x(t))\| + \|g(t, x(t))\|.
 \end{aligned}$$

Then, it follows that

$${}^C D_t^q \Xi(t, x(t)) \leq - [\rho_0 \|x(t)\| + \|f(t, x(t))\| - \|g(t, x(t))\|].$$

Next, using condition (C3), we have

$$(3.2) \quad {}^C D_t^q \Xi(t, x(t)) \leq 0.$$

Thus, from Theorem 2.1, the zero solution of the system of FrODEs (1.1) is uniformly stable. This result completes the proof of Theorem 3.1

Our next result studies the boundedness of solutions of the system of FrODEs (1.1).

Theorem 3.2. *The solutions of the system of FrODEs (1.1) are bounded at the infinity if conditions (C1)-(C3) are satisfied.*

Proof. Using conditions (C1)-(C3) from Theorem 3.1, we have (3.2), i.e.,

$${}^C D_t^q \Xi(t, x(t)) \leq 0.$$

Next, it is clear that

$$\Xi(t, x(t)) \leq \Xi(t_0, x(t_0)), \quad t \geq t_0.$$

As for the next step, we derive

$$\begin{aligned}
 \|x(t)\| &= |x_1(t)| + \dots + |x_n(t)| \\
 &= \Xi(t, x(t)) \\
 &\leq \Xi(t_0, x(t_0)) = \|x(t_0)\| = |x_1(t_0)| + \dots + |x_n(t_0)|,
 \end{aligned}$$

i.e., we have

$$\|x(t)\| \leq \|x(t_0)\|.$$

Let

$$\rho_1 = \|x(t_0)\| = |x_1(t_0)| + \dots + |x_n(t_0)| > 0.$$

Hence, we obtain

$$\|x(t)\| = |x_1(t)| + \dots + |x_n(t)| \leq \rho_1.$$

Thus, it is clear that if $t \rightarrow \infty$, then $\|x(t)\| \leq \rho_1$. This result completes the proof of Theorem 3.2.

Our next result deals with the asymptotic stability of the zero solution of the system of FrODEs (1.1).

Theorem 3.3. *The zero solution of the system of FrODEs (1.1) is asymptotically stable if conditions (C1), (C2) and (C4) are satisfied.*

Proof. Applying conditions (C1), (C2) as in Theorem 3.1, we have

$${}^C D_t^q \Xi(t, x(t)) \leq -\rho_0 \|x(t)\| - \|f(t, x(t))\| + \|g(t, x(t))\|.$$

As for the next step, using condition (C4) we derive

$$\begin{aligned} {}^C D_t^q \Xi(t, x(t)) &\leq -\rho_0 \|x(t)\| - f_0 \|x(t)\| + g_0 \|x(t)\| \\ &= -(\rho_0 + f_0 - g_0) \|x(t)\| \\ &\leq -(\rho_2) \|x(t)\| < 0, \|x(t)\| \neq 0. \end{aligned}$$

Hence, the zero solution of the system of FrODEs (1.1) is asymptotically stable by Theorem 2.2. This is the end of the proof of Theorem 3.3.

The following theorem shows the Mittag-Leffler stability of the zero solution of the system FrODEs (1.1).

Theorem 3.4. *The zero solution of the system of FrODEs (1.1) is Mittag-Leffler stable if conditions (C1), (C2) and (C4) are satisfied.*

Proof. Using conditions C1), (C2) and (C4) as in Theorem 3.3, we have

$${}^C D_t^q \Xi(t, x(t)) \leq -\rho_2 \|x(t)\| = -\rho_2 \Xi(t, x(t)),$$

i.e.,

$${}^C D_t^q \Xi(t, x(t)) \leq -\rho_2 \Xi(t, x(t)).$$

Using Lemma 2.1, we derive

$$\begin{aligned} \|x(t)\| &= \Xi(t, x(t)) \leq \Xi(t_0, x(t_0)) E_q(-\rho_2(t-t_0)^q) \\ &= \|x(t_0)\| E_q(-\rho_2(t-t_0)^q) \\ &= [m(x(t_0)) E_q(-\rho_2(t-t_0)^q)], \end{aligned}$$

where $m(x) = \|x(t)\|$, $m(0) = 0$, $m(x) \geq 0$, $m(x)$ is locally Lipschitz with Lipschitz constant $m_0 = 1$. Thus, the proof of Theorem 3.4 is completed by using Definition 2.2.

4. NUMERICAL APPLICATIONS

Example 4.1. Consider the following system of FrODEs with Caputo derivative, $q \in (0, 1)$:

$$(4.1) \quad \begin{pmatrix} {}^C_{t_0} D_t^q x_1(t) \\ {}^C_{t_0} D_t^q x_2(t) \end{pmatrix} = - \begin{bmatrix} 9 + \exp(-t) & 1 \\ 1 & 9 + \exp(-t) \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} - \begin{bmatrix} 2x_1(t) + \frac{x_1(t)}{1 + \exp(t) + |x_1(t)|} \\ 2x_2(t) + \frac{x_2(t)}{1 + \exp(t) + |x_2(t)|} \end{bmatrix} \begin{bmatrix} \frac{x_1(t)}{1 + \exp(2t) + |x_1(t)|} \\ \frac{x_2(t)}{1 + \exp(2t) + |x_2(t)|} \end{bmatrix}.$$

Comparing the systems of FrODEs (4.1) and (1.1), we have the following relations:

$$A(t) = \begin{bmatrix} 9 + \exp(-t) & 1 \\ 1 & 9 + \exp(-t) \end{bmatrix},$$

$$a_{ii}(t) - \sum_{j=1, j \neq i}^n |a_{ji}(t)| = 9 + \exp(-t) - 1 \geq 8 > 7 = \rho_0;$$

$$f(t, x(t)) = \begin{bmatrix} f_1(t, x_1(t), x_2(t)) \\ f_2(t, x_1(t), x_2(t)) \end{bmatrix} = \begin{bmatrix} 2x_1(t) + \frac{x_1(t)}{1 + \exp(t) + |x_1(t)|} \\ 2x_2(t) + \frac{x_2(t)}{1 + \exp(t) + |x_2(t)|} \end{bmatrix},$$

$$f(t, 0) = 0,$$

$$\begin{aligned} \|f(t, x(t))\| &= \left\| \begin{bmatrix} f_1(t, x_1(t), x_2(t)) \\ f_2(t, x_1(t), x_2(t)) \end{bmatrix} \right\| \\ &= \left\| \begin{bmatrix} 2x_1(t) + \frac{x_1(t)}{1 + \exp(t) + |x_1(t)|} \\ 2x_2(t) + \frac{x_2(t)}{1 + \exp(t) + |x_2(t)|} \end{bmatrix} \right\| \\ &\geq 2|x_1(t)| - \frac{|x_1(t)|}{1 + \exp(t) + |x_1(t)|} + 2|x_2(t)| - \frac{|x_2(t)|}{1 + \exp(t) + |x_2(t)|} \\ &\geq |x_1(t)| + |x_2(t)| = \|x(t)\|, \end{aligned}$$

$$f_0 = 1;$$

$$g(t, x(t)) = \begin{bmatrix} g_1(t, x_1(t), x_2(t)) \\ g_2(t, x_1(t), x_2(t)) \end{bmatrix} = \begin{bmatrix} \frac{x_1(t)}{1 + \exp(2t) + |x_1(t)|} \\ \frac{x_2(t)}{1 + \exp(2t) + |x_2(t)|} \end{bmatrix},$$

$$g(t, 0) = 0,$$

$$\begin{aligned} \|g(t, x(t))\| &= \left\| \begin{bmatrix} g_1(t, x_1(t), x_2(t)) \\ g_2(t, x_1(t), x_2(t)) \end{bmatrix} \right\| = \left\| \begin{bmatrix} \frac{x_1(t)}{1 + \exp(2t) + |x_1(t)|} \\ \frac{x_2(t)}{1 + \exp(2t) + |x_2(t)|} \end{bmatrix} \right\| \\ &\leq \frac{|x_1(t)|}{1 + \exp(t) + |x_1(t)|} + \frac{|x_2(t)|}{1 + \exp(t) + |x_2(t)|} \\ &\leq |x_1| + |x_2| = \|x\|, \end{aligned}$$

$$g_0 = 1;$$

As for the next step, from the above relations, we derive

$$\begin{aligned} & \rho_0 \|x(t)\| + \|f(t, x(t))\| - \|g(t, x(t))\| \\ & \geq 7 \|x(t)\| + \|x(t)\| - \|x(t)\| = 7 \|x(t)\| \geq 0 \end{aligned}$$

and

$$\rho_0 + f_0 - g_0 \geq 7 + 1 - 1 = 7 = \rho_2.$$

Considering the above discussion, we can verify that conditions (C1)-(C3) of Theorem 3.1 and Theorem 3.2 and conditions (C1), (C2) and (C4) of Theorem 3.3 and Theorem 3.4 are satisfied. For these reasons, the zero solution of the system of FrODEs (4.1) is uniformly stable, asymptotically stable and Mittag-Leffler stable and nonzero solutions of FrODEs (4.1) are bounded at infinity.

5. CONCLUSION

This paper investigates qualitative properties of solutions of a nonlinear system of FrODEs with Caputo fractional derivative. Indeed, here, a new perturbed system of FrODEs (1.1) with Caputo fractional derivative is taken into account. Four new results related to uniform stability, asymptotic stability, Mittag-Leffler stability of zero solution as well as boundedness of non-zero solutions of the system of FrODEs (1.1) are obtained. The results of this paper are proved by the second Lyapunov method. When we compare the main results of this paper with those obtained in the literature, our results are more general, suitable and convenient for applications. An example is given as numerical application to verify the applications of the conditions of the main results. The results of this paper have new contributions to the theory of FrODEs and the relevant literature

ACKNOWLEDGMENTS

The work of Ching-Feng Wen was supported by the Ministry of Science and Technology, Taiwan under Grant Number 110-2115-M-037-001.

REFERENCES

- [1] S. Abbas, M. Benchohra, J. E. Lazreg and Y. Zhou, *A survey on Hadamard and Hilfer fractional differential equations: analysis and stability*, Chaos Solitons Fractals **102** (2017), 47–71.
- [2] N. Aguila-Camacho, M. A. Duarte-Mermoud and J. A. Gallegos, *Lyapunov functions for fractional order systems*, Commun. Nonlinear Sci. Numer. Simul. **19** (2014), 2951–2957.
- [3] S. Ahmad and M. Rama Mohana Rao, *Theory of Ordinary Differential Equations. With Applications in Biology and Engineering*, Affiliated East-West Press Pvt. Ltd., New Delhi, 1999.
- [4] M. Benchohra, S. Bouriah and J. J. Nieto, *Existence and Ulam stability for nonlinear implicit differential equations with Riemann-Liouville fractional derivative*, Demonstr. Math. **52** (2019), 437–450.
- [5] M. Bohner, O. Tunç and C. Tunç, *Qualitative analysis of caputo fractional integro-differential equations with constant delays*, Comp. Appl. Math. **40** (2021). <https://doi.org/10.1007/s40314-021-01595-3>
- [6] T. A. Burton, *Liapunov Theory for Integral Equations with Singular Kernels and Fractional Differential Equations*, Theodore Allen Burton, Port Angeles, WA, 2012.
- [7] M.A. Duarte-Mermoud, N. Aguila-Camacho, J. A. Gallegos and R. Castro-Linares, *Using general quadratic Lyapunov functions to prove Lyapunov uniform stability for fractional order systems*, Commun. Nonlinear Sci. Numer. Simul. **22** (2015), 650–659.

- [8] M. Gözen and C. Tunç, *A new result on exponential stability of a linear differential system of first order with variable delays*, *Nonlinear Studies* **27** (2020), 275–284.
- [9] P. M. Guzmán, L. M. Lugo Motta Bittencurt and J. E. Nápoles Valdes, *On the stability of solutions of fractional non conformable differential equations*, *Stud. Univ. Babeş-Bolyai Math.* **65** (2020), 495–502.
- [10] Y. Han, N. Huang and J. C. Yao, *Connectedness and stability of the approximate solutions to generalized vector quasi-equilibrium problems*, *J. Nonlinear Convex Anal.* **18** (2017), 1079–1101.
- [11] A. A. Kilbas, H. M. Srivastava and J. J. Trujillo, *Theory and Applications of Fractional Differential Equations*, North-Holland Mathematics Studies, 204. Elsevier Science B.V., Amsterdam, 2006.
- [12] K. Lapin and C. Tunç, *Uniform-ultimate Poisson boundedness of solutions of P -perturbed systems of differential equations*, *Miskolc Mathematical Notes.* **21** (2020), 959–967.
- [13] Y. Li, Y. Q. Chen and I. Podlubny, *Stability of fractional-order nonlinear dynamic systems: Lyapunov direct method and generalized Mittag-Leffler stability*, *Comput. Math. Appl.* **59** (2010), 1810–1821.
- [14] S. Liu, W. Jiang, X. Li and X. F. Zhou, *Lyapunov stability analysis of fractional nonlinear systems*, *Appl. Math. Lett.* **51** (2016), 13–19.
- [15] K.S. Miller and B. Ross, *An Introduction to the Fractional Calculus and Fractional Differential Equations*, A Wiley-Interscience Publication, John Wiley & Sons, Inc., New York, 1993.
- [16] I. Podlubny, *Fractional Differential Equations. An introduction to Fractional Derivatives, Fractional Differential Equations, to Methods of Their Solution and Some of Their Applications*, Mathematics in Science and Engineering, 198. Academic Press, Inc., San Diego, CA, 1999.
- [17] J. Ren and C. Zhai, *Stability analysis of generalized neutral fractional differential systems with time delays*, *Appl. Math. Lett.* **116** (2021): 106987, 8 pp.
- [18] C. Tunç, *On the qualitative behaviors of a functional differential equation of second order*, *Appl. Appl. Math.* **12** (2017), 813–2842.
- [19] C. Tunç, *On the properties of solutions for a system of non-linear differential equations of second order*, *Int. J. Math. Comput. Sci.* **14** (2019), 519–534.
- [20] C. Tunç, *On the asymptotic analysis of boundedness of solutions of DDEs of second order*, *Applied Analysis and Optimization* **4** (2020), 133–147.
- [21] O. Tunç, *On the behaviors of solutions of systems of non-linear differential equations with multiple constant delays*, *RACSAM* **115** (2021). <https://doi.org/10.1007/s13398-021-01104-5>.
- [22] C. Tunç and O. Tunç, *On the boundedness and integration of non-oscillatory solutions of certain linear differential equations of second order*, *Journal of Advanced Research.* **7** (2016), 165–168.
- [23] C. Tunç and O. Tunç, *A note on the stability and boundedness of solutions to non-linear differential systems of second order*, *Journal of the Association of Arab Universities for Basic and Applied Sciences* **24** (2017), 169–175.
- [24] C. Tunç and O. Tunç, *On the stability, integrability and boundedness analyses of systems of integro-differential equations with time-delay retardation*, *Revista de la Real Academia de Ciencias Exactas, Físicas y Naturales. Serie A. Matemáticas* **15** (2021): Article Number: 115.
- [25] C. Tunç, O. Tunç, Y. Wang and J.C. Yao, *Qualitative analyses of differential systems with time-varying delays via Lyapunov-Krasovskii approach*, *Mathematics.* **9** (2021): 1196.
- [26] O. Tunç, C. Tunç and Y. Wang, *Delay-dependent stability, integrability and boundedness criteria for delay differential systems*, *Axioms.* **10** (2021): 138.
- [27] O. Tunç, —”O. Atan, C. Tunç and J. C. Yao, *Qualitative Analyses of Integro-Fractional Differential Equations with Caputo Derivatives and Retardations via the Lyapunov-Razumikhin Method*, *Axioms* **10** (2021): 58.
- [28] D. J. Vasundhara, F. A. Mc Rae and Z. Drici, *Variational Lyapunov method for fractional differential equations*, *Comput. Math. Appl.* **64** (2012), 2982–2989.
- [29] Y. Wang and T. Li, *Stability analysis of fractional-order nonlinear systems with delay*, *Math. Probl. Eng.* (2014), 8 pp.

- [30] Y. Wen, X. F. Zhou, Z. Zhang and S. Liu, *Lyapunov method for nonlinear fractional differential systems with delay*, Nonlinear Dynam. **82** (2015), 1015–1025.
- [31] S. P. Yang, *Asymptotic stability of a class of fractional neutral delay differential systems*, (Chinese) Acta Math. Appl. Sin. **39** (2016), 719–733.
- [32] B. Zhang, *Liapunov functionals and stability in fractional differential equations*, Dyn. Contin. Discrete Impuls. Syst. Ser. A Math. Anal. **22** (2015), 465–480.
- [33] Y. Zhou, *Basic Theory of Fractional Differential Equations*, World Scientific Publishing Co. Pte. Ltd., Hackensack, NJ, 2014.

*Manuscript received May 10 2021
revised August 29 2021*

O. TUNÇ

Baskale Vocational School, Van Yuzuncu Yil University, 65080, Campus, Van-Turkey
E-mail address: osmantunc89@gmail.com

C. TUNÇ

Department of Computer Programing, Department of Mathematics, Faculty of Sciences, Van Yuzuncu Yil University, 65080-Campus, Van-Turkey
E-mail address: cemtunc@yahoo.com

C. F. WEN

Center for Fundamental Science, and Research Center for Nonlinear Analysis and Optimization, Kaohsiung Medical University, Kaohsiung, 80708, Taiwan; Department of Medical Research, Kaohsiung Medical University Hospital, Kaohsiung, 80708, Taiwan
E-mail address: cfwen@kmu.edu.tw