# A FIXED SET THEOREM FOR SET-TO-SET MAPS 

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#### Abstract

A fixed set theorem in term of $T(A)=A$ for set-to-set Hausdorff continuous self-mappings on a family of all nonempty compact convex subset of a normed space was given by using an embedding idea by Radström [8].


## 1. Introduction

Let $X$ be a compact convex subset of a normed space. For a set-valued map $T: X \rightarrow 2^{X}, \bar{x} \in X$ is said to be a fixed point of $T$ if $T(\bar{x}) \ni \bar{x}$. Nadler established a fixed point theorem for set-valued maps in [7] which is an extension of the Banach contraction principle, Mizoguchi and Takahashi have extended Nadler's results in [6]. Also Fakhar, Soltani and Zafarani gave a maximal invariant set (fixed set) theorem for set-valued maps in [3].

On the other hand, for a set-to-set map $T: 2^{X} \rightarrow 2^{X}$ and a nonempty set $A \in 2^{X}$, there are four type fixed set notions which are generalizations of the fixed point notion:
(1) $T(A)=A$;
(2) $T(A) \subset A$;
(3) $T(A) \supset A$;
(4) $T(A) \cap A \neq \emptyset$.

We can find the following previous works for such fixed set theorems: Pradip, Binayak and Murchana showed a fixed set theorem in term of $T(A) \supset A$ in [2], which is a generalization of Nadler's result, and Robert, Klaus and Bradon showed a fixed set theorem in term of $T(B)=B$ for a monotone map $T$ under the existence of $A$ such that $T(A) \subset A$ in [1], and applied to study of a boundary value problem for a system of differential equations. In this paper, we give another fixed set theorem for set-to-set maps, by using an embedding idea in [8], which is a generalization of the following Schauder fixed point theorem, see [9]:

Theorem 1.1. Let $X$ be a nonempty convex subset of a normed space $E$, and let $T$ be a continuous self-mapping on $X$. If $T(X)$ is compact, then there exists $\bar{x} \in X$ such that $T(\bar{x})=\bar{x}$.

## 2. Main Results

Throughout this paper, let $E$ be a normed space, let $X$ be a nonempty compact convex subset of $E$, and let $\mathcal{C}_{X}$ be the family of all nonempty compact convex subsets of $X$.

[^0]Lemma 2.1. Define $H: \mathcal{C}_{X} \times \mathcal{C}_{X} \rightarrow[0,+\infty)$ by

$$
H(A, B):=\max \left\{\sup _{a \in A} \inf _{b \in B}\|a-b\|, \sup _{b \in B} \inf _{a \in A}\|a-b\|\right\}
$$

for any $A, B \in \mathcal{C}_{X}$. Then $H$ is a metric on $\mathcal{C}_{X}$, which is called the Hausdorff metric, and the metric space $\left(\mathcal{C}_{X}, H\right)$ is compact.

Proof. We give a proof based on the non-convex version, see [4]. Since $X$ is compact, that is, $X$ is totally bounded, for any $\varepsilon>0$, there exists a finite set $Y \subset X$ such that

$$
\min _{y \in Y} d(x, y)<\varepsilon \text { for any } x \in X
$$

For any $C \in \mathcal{C}_{X}$, put $S=\{y \in Y \mid d(C, y)<\varepsilon\}$, then $H(C, S)<\varepsilon$ holds, that is, $H(C, \operatorname{co} S)<\varepsilon$ holds. Put a finite subfamily $\mathcal{T}=\left\{\operatorname{co} S \mid S \in 2^{Y}\right\}$, then $\mathcal{T} \subset \mathcal{C}_{X}$ and

$$
\min _{T \in \mathcal{T}} H(C, T)<\varepsilon \text { for any } C \in \mathcal{C}_{X}
$$

This shows that $\left(\mathcal{C}_{X}, H\right)$ is also total bounded. Next, for any Cauchy sequence $\left\{A_{n}\right\} \subset \mathcal{C}_{X}$, define

$$
A:=\left\{x \in X \mid \exists\left\{x_{n}\right\} \subset X \text { s.t. } x_{n} \rightarrow x, x_{n} \in A_{n} \forall n \in \mathbb{N}\right\}
$$

then we can see that $A$ is a nonempty compact convex subset of $X$ and $\left\{A_{n}\right\}$ converges to $A$ with respect to the Hausdorff metric $H$. Then $\left(\mathcal{C}_{X}, H\right)$ is complete, and consequently $\left(\mathcal{C}_{X}, H\right)$ is compact.

Now we give the main theorem.
Theorem 2.2. Let $\mathcal{A}$ be a subfamily of $\mathcal{C}_{X}$ satisfying

$$
\begin{equation*}
A, B \in \mathcal{A}, \lambda \in(0,1) \Rightarrow(1-\lambda) A+\lambda B \in \mathcal{A} \tag{2.1}
\end{equation*}
$$

and let $T: \mathcal{A} \rightarrow \mathcal{A}$ be continuous with respect to the Hausdorff metric $H$. If either the following (i) or (ii) holds:
(i) $\mathcal{A}$ is closed with respect to the Hausdorff metric $H$,
(ii) $T(\mathcal{A}):=\{T(A) \mid A \in \mathcal{A}\}$ is closed with respect to the Hausdorff metric $H$, then $T$ has a fixed set, that is, there exists $\bar{A} \in \mathcal{A}$ such that $T(\bar{A})=\bar{A}$.

Proof. We may assume (ii). Indeed, if (i) holds, then $\mathcal{A}$ is compact because $\mathcal{A}$ is closed and $\mathcal{C}_{X}$ is compact with respect to the Hausdorff metric $H$, therefore, the image $T(\mathcal{A})$ is also compact because $T$ is continuous.

Let $\mathcal{C}$ be the family of all nonempty compact convex subsets of $E$, and define a binary relation $\equiv$ on $\mathcal{C}^{2}$ by, for all $(A, B),(C, D) \in \mathcal{C}^{2}$,

$$
(A, B) \equiv(C, D) \text { if } A+D=B+C
$$

then $\equiv$ is an equivalence relation on $\mathcal{C}^{2}$. The cancellation low on $\mathcal{C}$, that is,

$$
A+B \subset A+C \Rightarrow B \subset C
$$

is essential to show the equivalence. Define the quotient space

$$
\mathcal{C}^{2} / \equiv:=\left\{[A, B] \mid(A, B) \in \mathcal{C}^{2}\right\}
$$

where

$$
[A, B]:=\left\{(C, D) \in \mathcal{C}^{2} \mid(A, B) \equiv(C, D)\right\}
$$

and define the following addition and scholar multiplication on $\mathcal{C}^{2} / \equiv$ by

$$
\begin{gathered}
{[A, B]+[C, D]=[A+C, B+D],} \\
\lambda[A, B]=\left\{\begin{array}{cc}
{[\lambda A, \lambda B]} & \text { if } \lambda \geq 0 \\
{[-\lambda B,-\lambda A]} & \text { if } \lambda<0
\end{array}\right.
\end{gathered}
$$

for any $[A, B],[C, D] \in \mathcal{C}^{2} / \equiv$ and $\lambda \in \mathbb{R}$, then $\mathcal{C}^{2} / \equiv$ is a vector space over $\mathbb{R}$. Also define

$$
\|[A, B]\|=H(A, B)
$$

for each $[A, B] \in \mathcal{C}^{2} / \equiv$, then $\left(\mathcal{C}^{2} / \equiv,\|\cdot\|\right)$ becomes a normed space. For details about these arguments, see $[5,8]$.

Define

$$
\begin{array}{rllc}
\psi: & \mathcal{A} & \rightarrow & \mathcal{C}^{2} / \equiv \\
\Psi & & \cup \\
A & \longmapsto & {[A,\{0\}] .}
\end{array}
$$

Note that

$$
\|\psi(A)-\psi(B)\|=\|[A,\{0\}]-[B,\{0\}]\|=\|[A, B]\|=H(A, B)
$$

for any $A, B \in \mathcal{C}_{X}$. Consequently, $\psi$ is continuous because

$$
\left\|\psi\left(A_{n}\right)-\psi(A)\right\|=H\left(A_{n}, A\right) \rightarrow 0
$$

for a sequence $\left\{A_{n}\right\}_{n \in \mathbb{N}} \subset \mathcal{A}$ converges to $A \in \mathcal{A}$ with respect to the Hausdorff metric $H$. Also $\psi(\mathcal{A})$ is a convex subset of $\mathcal{C}^{2} / \equiv$. Indeed, for any $\psi(A), \psi(B) \in \psi(\mathcal{A})$ and $\lambda \in(0,1)$, from

$$
(1-\lambda) \psi(A)+\lambda \psi(B)=[(1-\lambda) A+\lambda B,\{0\}]=\psi((1-\lambda) A+\lambda B)
$$

and $(1-\lambda) A+\lambda B \in \mathcal{A}$, then $(1-\lambda) \psi(A)+\lambda \psi(B) \in \psi(\mathcal{A})$.
Consider a self-mapping on convex set $\psi(\mathcal{A})$ defined by

$$
\begin{array}{cccc}
\mathcal{T}: & \psi(\mathcal{A}) & \rightarrow & \psi(\mathcal{A}) \\
\Psi & & \cup \\
{[A,\{0\}]} & \longmapsto & {[T(A),\{0\}]}
\end{array}
$$

then $\mathcal{T}$ is continuous. Indeed, if a sequence $\left\{\psi\left(A_{n}\right)\right\} \subset \psi(\mathcal{A})$ converges to $\psi(A) \in$ $\psi(\mathcal{A})$, that is $\left\|\psi\left(A_{n}\right)-\psi(A)\right\| \rightarrow 0$, then $H\left(A_{n}, A\right) \rightarrow 0$ and

$$
\left\|\mathcal{T}\left(\psi\left(A_{n}\right)\right)-\mathcal{T}(\psi(A))\right\|=\left\|\left[T\left(A_{n}\right),\{0\}\right]-[T(A),\{0\}]\right\|=H\left(T\left(A_{n}\right), T(A)\right)
$$

Since $T$ is continuous with respect to $H$, then $H\left(T\left(A_{n}\right), T(A)\right) \rightarrow 0$. This shows $\mathcal{T}$ is continuous. Also $\mathcal{T}(\psi(\mathcal{A}))$ is compact because $T(\mathcal{A})$ is compact, $\psi$ is continuous, and

$$
\begin{aligned}
\mathcal{T}(\psi(\mathcal{A})) & =\{\mathcal{T}(\psi(A)) \mid A \in \mathcal{A}\} \\
& =\{\mathcal{T}([A,\{0\}]) \mid A \in \mathcal{A}\} \\
& =\{[T(A),\{0\}] \mid A \in \mathcal{A}\} \\
& =\{\psi(T(A)) \mid A \in \mathcal{A}\} \\
& =\psi(T(\mathcal{A})) .
\end{aligned}
$$

By using Theorem 1.1, there exists $\bar{A} \in \mathcal{A}$ such that $\mathcal{T}(\psi(\bar{A}))=\psi(\bar{A})$, that is, $T(\bar{A})=\bar{A}$.

Remark 2.3. It is clear that Theorem 2.2 is different from the previous fixed set theorems in [1, 2].

We can obtain the following corollaries by using Theorem 2.2:
Corollary 2.4. Let $T$ be a continuous self-mapping on $\mathcal{C}_{X}$ with respect to the Hausdorff metric $H$. Then $T$ has a fixed set, that is, there exist $\bar{A} \in \mathcal{C}_{X}$ such that $T(\bar{A})=\bar{A}$.

Proof. Put $\mathcal{A}:=\mathcal{C}_{X}$, then we can see that $\mathcal{A}$ is closed with respect to $H$ satisfying (2.1). Therefore we can apply Theorem 2.2 to show the existence of fixed sets of $T$.

Corollary 2.5 (Theorem 1.1). Let $X$ be a nonempty convex subset of a normed space $E$, and let $T$ be a continuous self-mapping on $X$. If $T(X)$ is compact, then there exists $\bar{x} \in X$ such that $T(\bar{x})=\bar{x}$.

Proof. Put $\mathcal{A}:=\{\{x\} \mid x \in X\}$, then we can see that $\mathcal{A}$ is closed with respect to $H$ satisfying (2.1) and $\hat{T}: \mathcal{A} \rightarrow \mathcal{A}$, defined by $\hat{T}(\{x\})=\{T(x)\}$, is continuous with respect to the Hausdorff metric $H$. Therefore we can apply Theorem 2.2 to show the existence of fixed sets of $T$.
Remark 2.6. Theorem 2.2 does not guarantee an existence fixed set $\bar{A}$ is a nonsingleton set. However by constructing $\mathcal{A}$ which does not include singleton sets, every existence fixed set becomes non-singleton. We give the following examples to explain this remark:
Example 2.7. Let $X=[0,2]^{2}$ and

$$
\mathcal{A}=\left\{B\left(x_{1}, x_{2}, r\right) \mid B\left(x_{1}, x_{2}, r\right) \subset X,\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}, r \geq 0\right\}
$$

where $B\left(x_{1}, x_{2}, r\right)=\left\{\left(y_{1}, y_{2}\right) \in \mathbb{R}^{2} \mid\left(y_{1}-x_{1}\right)^{2}+\left(y_{2}-x_{2}\right)^{2} \leq r^{2}\right\}$. Then $\mathcal{A} \subset \mathcal{C}_{X}$ is closed with respect to the Hausdorff metric $H$. Hence each continuous self-mapping on $\mathcal{A}$ with respect to $H$ has a fixed set from Theorem 2.2. For example, define

$$
T\left(B\left(x_{1}, x_{2}, r\right)\right)=B\left(x_{2}, x_{1}, r^{2}\right)
$$

then we can check that $T: \mathcal{A} \rightarrow \mathcal{A}$ is continuous with respect to $H$ and then there exists a fixed set $\bar{A} \in \mathcal{A}$ such that $T(\bar{A})=\bar{A}$. However, we can not see whether an existence fixed set $\bar{A}$ is a non-singleton set or not. Indeed, $B(1,1,1)$ and $B(x, x, 0)$, $0 \leq x \leq 2$, are fixed sets of $T$. On the other hand, let

$$
\mathcal{A}^{\prime}=\left\{B\left(x_{1}, x_{2}, r\right) \mid B\left(x_{1}, x_{2}, r\right) \subset X,\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}, r>0\right\}
$$

and assume that a self-mapping $T$ on $\mathcal{A}^{\prime}$ has a fixed set $\bar{A}$, then $\bar{A}$ should be nonsingleton. However $\mathcal{A}^{\prime}$ is not closed with respect to $H$ and Theorem 2.2 can not be applied to the situation.
Example 2.8. Let $X=[0,4] \times[0,4] \subset \mathbb{R}^{2}$ and let

$$
\mathcal{A}=\{[a, b] \times[c, d] \mid 0 \leq a \leq b \leq 4,0 \leq c \leq d \leq 4,(b-a)(d-c)=1\}
$$

Consider a self-mapping $T: \mathcal{A} \rightarrow \mathcal{A}$ defined by

$$
T([a, b] \times[c, d])=\left[a+t_{W}(a)-h, b-t_{E}(b)+h\right] \times\left[c+t_{S}(c)-h, d-t_{N}(d)+h\right]
$$



Figure 1. The orbit $\left\{T^{n}([0,1] \times[0,1])\right\}$ in Example 2.8
where $t_{W}(a)=3(4-a) / 16, t_{E}(b)=b / 8, t_{S}(c)=5(4-c) / 32, t_{N}(d)=3 d / 32$, and $h$ is the biggest solution of the following quadratic function:

$$
\left(b-t_{E}(b)-a-t_{W}(a)+2 h\right)\left(d-t_{N}(d)-c-t_{S}(c)+2 h\right)=1
$$

Since $\mathcal{A}$ does not include any singleton, every fixed set $\bar{A}$ of $T$ is non-singleton. We can see that the only fixed set is $[4-k / 6, k / 4] \times[4-k / 5, k / 3]$ where $k=$ $(171-3 \sqrt{249}) / 20$. This example shows a model of residence movement against natural threats from north, south, east, and west. The orbit $\left\{T^{n}([0,1] \times[0,1])\right\}$ is given in Figure 1.
Example 2.9. Let $X$ be a nonempty compact convex subset of a normed space $E$ and for any $\varepsilon>0$, define

$$
\mathcal{A}_{\varepsilon}=\left\{A \subset \mathcal{C}_{X} \mid \text { there exists } x \in X \text { such that } B(x, \varepsilon) \subset A\right\}
$$

where $B(x, \varepsilon)=\{y \in X \mid\|y-x\| \leq \varepsilon\}$. Then we can check that $\mathcal{A}_{\varepsilon}$ is closed with respect to the Hausdorff metric $H$ and (2.1). If $T$ is a continuous self-mapping on $\mathcal{A}_{\varepsilon}$, then there exists a fixed set $\bar{A} \in \mathcal{A}_{\varepsilon}$. Clearly, $\bar{A}$ is a non-singleton set.

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